Chapter 31

ACTUATOR, WESTERN, TYPE ERJ60, Mk. 12

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LEADING PARTICULARS

Actuate	or, Type	: ERJ	60, Mk	. 12						
Voltage	range		****			2112	 	1	8 to 2	9 volts d.c.
Rating	****			***	***		 ****			I min.
Normal	full load	i		4000	****		 2.222		2002	60 lb. in
Maximi	ım work	ing lo	ad				****		1111	85 lb. in.
Angulai	travel o	f cou	bling				90	deg. (+	0 deg	. —2 deg.)
Weight	****							****		2 lb. 5 oz.
Overall	length	14.6.6.6								6.10 in.
Electric	al plug	,					 Mk	. 3 Bree	ze (C	Z.27164/1)

Description

1. The Western Type ERJ60 series of actuators is described in A.P.4343, Vol. 1, Sect. 17. The Mk. 12 varies from others in this series only in amount of angular travel of the coupling with its visual indicator and in the type of electrical connection plug.

Application and loading

2. The snap action limit switches in the Mk. 12 are adjusted during assembly to permit 90° angular travel of the coupling shaft. This adjustment requires the use of a manufacturers special rig and no attempt should be made to alter the setting. Detail of the movement of the coupling shaft relative to the mounting flange is shown in fig. 1. The operating times under various

loadings at nominal 28 volts are as follows:-

Load (lb. in.)	Max. current (amp.)	90° Travel (Sec.)
0	3	$2 \cdot 2$
30	3.8	2.6
60	$4 \cdot 2$	3.3

Electrical connection

3. A Mk. 3 miniature Breeze, 6-pole plug is fitted of which pin F is not used. When connecting the free socket to this plug care must be exercised to ensure correct alignment and so avoid damaging the moulded projection of the plug.

(A.L. 3, Oct. 57)

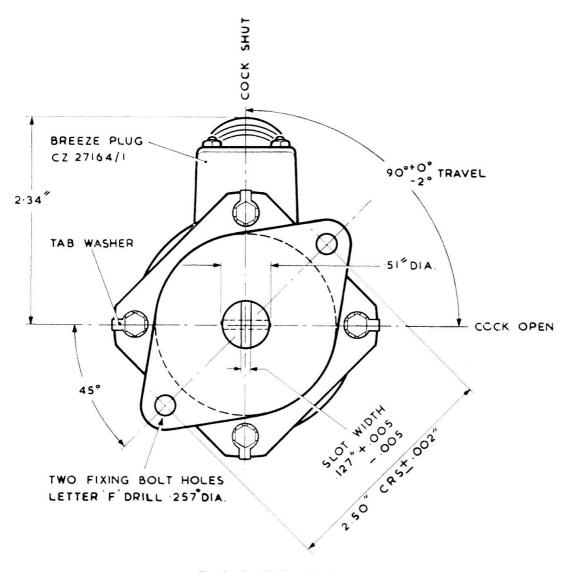


Fig. I. Installation drawing

Chapter 32

ACTUATOR, WESTERN, TYPE ERJ 60, Mk. 19

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LEADING PARTICULARS

Actuator, Wester	n type	ERJ	60, Mk.	19			Store	s Ref.	5W/1393
Voltage range		55.55	5555		5555		16	8 to 2	9 volt d.c.
Nominal current				****		****	to one		4 · 2 amp.
Stall current					****				6.5 amp.
Normal working load									60 lb/in.
Maximum working loa	ad	,							85 lb/in.
Angular travel of coup	oling				****		8.	5 deg.	, +0 deg. -2 deg.
Time of angular trave	l at nor	ninal l	oad						1 · 35 sec.
Distance between fixing	ng centi	res					2.5	in. ±	0.002 in.
Rating of motor									I min.
Temperature range						60	deg. C.	to + 9	90 deg. C.
Weight		****			****	****	****		2 lb. 5 oz.

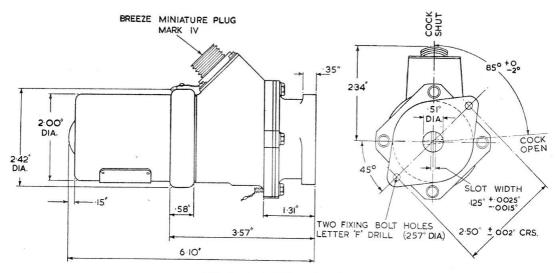


Fig. I. Installation drawing

Introduction

1. The rotary actuator, Type ERJ 60, Mk. 19, is designed to provide a torque, clockwise or anticlockwise as necessary, for situations requiring a rotational movement under remote control, within the ranges given under the heading Leading Particulars. It is rated to operate for one minute at a nominal load of 60 lb./in. with a current consumption not exceeding 4·3 amp.

DESCRIPTION

2. The Western Type ERJ 60 series of actuators is described in A.P.4343, Vol. 1, Sect. 17, Chap. 1 and App. 7. The Mk. 19 differs from others in this series in the amount of angular travel of the couplings, operating times and current consumption.

Application and loading

3. The limit switches are adjusted during manufacture to provide 85 deg. angular travel of the coupling shaft. All necessary information concerning the movement of the coupling shaft relative to the mounting flange is given in the installation drawing (fig. 1). A functional test should be performed by connecting the actuator to a 28-volt d.c. supply and applying loads of 0, 30 and 60 lb./in. The maximum current consumption and the time the coupling takes to complete its 85 deg. angular travel should not exceed the values given in the following table:—

Load	Max. Current	Max. Time
(lb./in.)	(amp.)	(sec.)
O	3.1	1.15
30	3.7	1.25
60	$4 \cdot 3$	1.35

Electrical connection

4. Electrical connections are identical with those described in A.P.4343, Vol. 1, Sect. 17, Chap. 1, and App. 7, dealing with Western type actuators. Internal wiring connections are given in the circuit diagram, (fig. 2) of the Appendix.

Installation and servicing

5. Installation and servicing instructions are given in A.P.4343, Vol. 1, Sect. 17, Chap. 1 and App. 7.

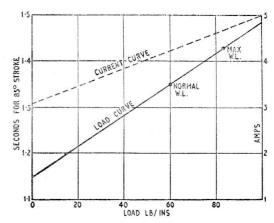


Fig. 2. Performance curves of motor